# A Bidirectional Three-Phase Push-Pull Converter With Dual Asymmetrical PWM Method 

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#### Abstract

This paper proposes a new bidirectional three-phase push-pull converter that has a simple structure and achieves zerovoltage switching turn-on of switches. Also, due to use of a single inductor, an imbalance among phase currents on the low-voltage high-current side is trivial in the proposed converter although no current sharing control is employed. In this paper, a new dual asymmetrical pulse width modulation (PWM) switching method is proposed for bidirectional power flow control with seamless mode change. The proposed switching method offers reduced circulating current and makes the converter easier to implement compared to the PWM plus phase shift-based control method since it is a general PWM method having two independent duty cycle controls on each side. Experimental results from a $3-\mathrm{kW}$ prototype are provided to validate the proposed concept.


Index Terms-Bidirectional dc-dc converter, push-pull, three-phase.

## I. Introduction

RECENTLY, high-power bidirectional dc-dc converters (BDCs) have aroused much interest in many applications such as energy storage systems, uninterruptible power supplies, solid-state transformers, electric vehicles, etc.

In particular, isolated BDCs have been used for the applications where bidirectional power flow with high-voltage stepup ratio and/or galvanic isolation is required, and a variety of topologies with high-frequency transformers have been proposed in [1]-[10]. BDCs based on flyback converters [1]-[3] can achieve soft-switching and clamping of surge voltage using auxiliary components. The power density can be improved in some low-power applications. But they are not suitable for highpower application due to stored energy in the transformer. A dual active bridge (DAB) converter [11] has symmetric structure and can achieve zero-voltage switching (ZVS) without using auxiliary components. However, the converter has a limited ZVS range and high circulating currents under wide voltage variation. In order to overcome the problems, many advanced modulation strategies for the DAB converter have been presented [12]-[18]. The most serious problem associated with the low impedance

[^0]nature of the voltage-fed converter is that the magnetic core saturation that can be caused by a possible flux imbalance may lead to switch failure. A BDC based on dual half-bridge converters [5] has halved the component count compared to the dual full-bridge topologies and guarantees volt-sec balance of the transformer. By controlling two control variables of duty and phase, current stresses on the switching devices and transformer could be kept minimum. However, large current rating of capacitors is an obstacle to selection of proper capacitors in high-power applications.

In order to overcome the problem associated with high device stresses when implemented with the single-phase dc-dc converter mentioned above, the three-phase dc-dc converter has been introduced in high-power applications [11], [19]-[36].

Generally, the three-phase dc-dc converter has several advantages over its single-phase counterpart: easy switch selection due to reduced current rating, reduction of the input and output filters' volume due to increased effective switching frequency by a factor of three, and reduction in transformer size due to better transformer utilization [27].

A three-phase DAB converter [11], [20], [29] has basically voltage-fed natures on both low-voltage side (LVS) and highvoltage side (HVS). The three-phase DAB converter also suffers from issues on narrow ZVS region, increased circulating current under wide voltage range operation, and magnetic core saturation of the transformer as the single-phase DAB converter does. A phase-shift three-phase bidirectional series-resonant converter [33] processes power in a sinusoidal manner and achieves soft switching, and therefore, the switching losses and noise can be significantly reduced. However, a tolerance of the resonant elements could be an impediment to high volume production of the converter.

The PWM plus phase shift (PPS) method [6] has been applied to the three-phase BDC based on the current-fed converter on the LVS and the voltage-fed converter on the HVS [34], [35]. The converter has several advantages such as minimized RMS values of current in switches and transformers, maintainable ZVS conditions over a wide range, and free direction change of the power flow. However, possible three-phase currents imbalance on the low-voltage high-current side due to tolerance of three inductors could be a challenging issue since it may cause overrating of switches, magnetic core saturation, and unequal thermal distribution, especially at high-power applications. A sophisticated control strategy has been proposed for balancing the three-phase inductor currents [37], making the controller to be complicated.

In this paper, a three-phase push-pull BDC with active clamping is proposed for high-power applications. The features of the proposed converter are as follows:


Fig. 1. Proposed bidirectional three-phase push-pull converter.


Fig. 2. Switching pattern of the DAPWM. (a) Boost operation. (b) Buck operation.

1) owing to inherent boost characteristics, the turn-ratio of the transformer can be reduced and the current ripple on the LVS is small;
2) the circulating current can be reduced by regulating the capacitor voltage on the LVS;
3) the magnetic core saturation caused by flux imbalance of the transformer is greatly relieved due to high impedance nature at the current-fed side [38];
4) no current-sharing control is needed since imbalance among phase currents on the low-voltage high-current side is trivial.
Also, a new dual asymmetrical pulse width modulation (DAPWM) switching method is proposed for bidirectional power flow control with seamless mode change. Further, owing to the use of two independent duty cycles, circulating currents can be reduced by matching the primary voltage with the secondary voltage referred to the primary. Besides, the proposed DAPWM method is easier to implement compared to the PPS method since it is a general PWM method having two independent duty cycle controls on each side.

## II. Proposed Converter

The proposed converter is basically a three-phase current-fed push-pull converter with active clamp [27], as shown in Fig. 1. The LVS of the proposed converter includes a three-phase switch bridge consisting of six switches $S_{L 1}-S_{L 6}$, clamp capacitor
$C_{C}$, and input filter inductor $L_{f}$ which is operated at three times the switching frequency. The HVS of the proposed converter is a three-phase switch bridge consisting of six switches $S_{H 1}-S_{H 6}$. The three-phase windings of the transformer are configured in $Y-Y$ connection. The neutral point of the threephase primary winding is connected to the input source through the input filter inductor. Note that a three-leg core must be used for proper operation of the proposed converter.

## A. Switching Method

Fig. 2 shows the switching pattern of the proposed DAPWM method for a phase of the converter. Two control variables, $D_{L}$ and $D_{H}$, are used for both forward (boost) and reverse (buck) operation. Duty cycles, $D_{L}$ and $1-D_{L}$, of the top and bottom switches of the LVS are used to maintain constant capacitor voltage $V_{C c}$ under varying LVS voltage condition. The voltage across $C_{c}$ is determined by following equation:

$$
\begin{equation*}
V_{C c}=\frac{V_{L}}{D_{L}} \tag{1}
\end{equation*}
$$

In the meanwhile, duty cycles, $D_{H}$ and $1-D_{H}$, of the top and bottom switches of the HVS are used to control the power flow between the LVS and HVS. The direction of power flow is determined by relative magnitude of the two duty cycles: $D_{L}<D_{H}$ for boost operation and $D_{L}>D_{H}$ for buck operation. The three switch pairs are interleaved with $120^{\circ}$ phase shift, which leads to an increased effective switching frequency, thereby reducing input-current ripple.

## B. Operating Principles

In this section, the operating principles of the boost and buck operations of the proposed converter are described in detail. The key waveforms and operation stages of the proposed converter for boost operation are shown in Figs. 3 and 4, respectively. The behavior of the converter in the one-third switching cycle can be described by three stages. Fig. 5 shows simplified equivalent circuits of each stage for detailed circuit analysis. For the sake of simplicity, it is assumed that the controlled voltage across $C_{C}$ is equal to $V_{H} / N$, where $N$ is turn ratio of transformer $\left(N_{S} / N_{P}\right)$,


Fig. 3. Key waveforms of the proposed converter with DAPWM (boost operation).
the current through $L_{f}$ is constant during the switching period $T_{S}$, and leakage inductances of each phase are $L_{k}$.

Stage I $\left[t_{0}-t_{1}\right]$ : Before $t_{0}$, switches $S_{L 2}, S_{L 4}, S_{L 5}, S_{H 2}, S_{H 4}$, and $S_{H 5}$ are being turned ON. At $t_{0}$, switches $S_{L 2}$ and $S_{H 2}$ are turned OFF, and switches $S_{L 1}$ and $S_{H 1}$ are turned ON, which causes changes in the voltages across the leakage inductors and the voltage can be obtained from Fig. 5(a). Thus, the slopes of the phase currents flowing through the leakage inductors can be expressed as follows:

$$
\begin{align*}
\frac{d i_{a}}{d t} & =\frac{d i_{c}}{d t}=\frac{N V_{C c}-V_{H}}{3 N L_{k}}  \tag{2}\\
\frac{d i_{b}}{d t} & =\frac{2\left(V_{H}-N V_{C c}\right)}{3 N L_{k}} \tag{3}
\end{align*}
$$

Because $V_{C c}$ is equal to $V_{H} / N$, the slopes of each current flowing through the leakage inductors are zero, meaning all the phase current are constant in this stage. During this stage, the power is transferred from LVS to HVS. At HVS, the current flows only through $S_{H 4}$ and $S_{H 5}$, although switch $S_{H 1}$ is being turned ON. Note that $S_{L 1}$ is turned ON under ZVS condition, and the ZVS current is the same as phase current $i_{a}\left(t_{1}\right)=$ $-I_{L} / 3$.

Stage II [ $\left.t_{1}-t_{2}\right]$ : At $t_{1}$, switch $S_{L 5}$ is turned OFF, and $S_{L 6}$ is turned ON under ZVS condition. It can be seen from Fig. 5(b)


Fig. 4. Operation stages of the proposed converter (boost operation). (a) $t_{0}-t_{1}$. (b) $t_{1}-t_{2}$. (c) $t_{2}-t_{3}$.
that $i_{c}$ starts to decrease with the slope which is determined by

$$
\begin{equation*}
\frac{d i_{c}}{d t}=\frac{-N V_{C c}-V_{H}}{3 N L_{k}} \tag{4}
\end{equation*}
$$

As $i_{c}$ decreases, phase currents $i_{a}$ and $i_{b}$ increase with the slopes determined, respectively, by

$$
\begin{align*}
\frac{d i_{a}}{d t} & =\frac{2 N V_{C c}-V_{H}}{3 N L_{k}}  \tag{5}\\
\frac{d i_{b}}{d t} & =\frac{-N V_{C c}+2 V_{H}}{3 N L_{k}} \tag{6}
\end{align*}
$$

Stage III $\left[t_{2}-t_{3}\right]$ : At $t_{2}$, switch $S_{H 5}$ is turned OFF, and $S_{H 6}$ is turned ON under ZVS condition. The slopes of the phase currents can be obtained from Fig. 5(c) as follows:

$$
\begin{align*}
\frac{d i_{a}}{d t} & =\frac{2\left(N V_{C c}-V_{H}\right)}{3 N L_{k}}  \tag{7}\\
\frac{d i_{b}}{d t} & =\frac{d i_{c}}{d t}=\frac{-N V_{C c}+V_{H}}{3 N L_{k}} \tag{8}
\end{align*}
$$

All the phase currents are constant because $V_{C c}$ is equal to $V_{H} / N$. This is the power transfer mode such as Stage I. At HVS, the current flows only through $S_{H 1}$ and $S_{H 6}$ although $S_{H 4}$ is being turned ON. At $t_{3}$, switches $S_{L 4}$ and $S_{H 4}$ are turned OFF, and $S_{L 3}$ and $S_{H 3}$ are turned ON. Note that switches $S_{H 3}$ is turned ON and $S_{H 4}$ is turned OFF under ZCS condition,


Fig. 5. Equivalent circuit for each mode (boost operation). (a) $t_{0}-t_{1}$. (b) $t_{1}-t_{2}$. (c) $t_{2}-t_{3}$.


Fig. 6. Key waveforms of the proposed converter with DAPWM (buck operation).
respectively. The rest of the switching cycle is repetition of these operation stages.

The key waveforms and operation stages of the proposed converter for buck operation are shown in Figs. 6 and 7. In the buck operation, the proposed converter with DAPWM method has three operating stages within a one-third switching cycle. Detailed explanation of operating stages is omitted here since the operating principle of the buck operation is very similar to the boost operation.

## C. ZVS Condition

Most of the switches of the proposed converter achieve softswitching except for LVS top switches in buck mode. Tables I

(a)

(b)

(c)

Fig. 7. Operation stages of the proposed converter (buck operation). (a) $t_{0}-t_{1}$. (b) $t_{1}-t_{2}$. (c) $t_{2}-t_{3}$.

TABLE I
Switching Characteristic of the Proposed Converter

|  | Boost mode | Buck mode |
| :--- | :---: | :---: |
| LVS top switches | ZVS turn-on | Hard switching |
| LVS bottom switches | ZVS turn-on | ZVS turn-on |
| HVS top switches | ZCS turn-on | ZCS turn-on |
| HVS bottom switches | ZVS turn-on \& ZCS turn-off | ZVS turn-on \& ZCS turn-off |

and II show the switching characteristics and ZVS currents of the switches, respectively. Fig. 8 shows the ZVS regions of both LVS and HVS bottom switches under LVS voltage variation.


Fig. 8. ZVS currents of the bottom switches ( $V_{H}=380 \mathrm{~V}, L_{k}=3 \mu \mathrm{H}, N=2, f_{s}=50 \mathrm{kHz}$, and $C_{o s s}=1650 \mathrm{pF}$ ). (a) LVS in boost mode. (b) LVS in buck mode. (c) HVS in boost and buck mode.

TABLE II
ZVS Currents of the Switches

|  | Boost mode | Buck mode |
| :--- | :---: | :---: |
| LVS top switches | $-\frac{I_{L}}{3}$ | - |
| LVS bottom switches | $\frac{-I_{L}}{3}+\frac{\left.V_{H} D_{H}-D_{L}\right)}{3 N f_{s} L_{k}}$ | $\frac{I_{L}}{3}-\frac{V_{H}\left(D_{H}-D_{L}\right)}{3 N f_{s} L_{k}}$ |
| HVS top switches | $-\frac{V_{H}\left(D_{H}-D_{L}\right)}{3 f_{s} L_{k} N^{2}}$ | $-\frac{V_{H}\left(D_{H}-D_{L}\right)}{3 f_{s} L_{k} N^{2}}$ |
| HVS bottom switches |  |  |



Fig. 9. Waveforms of winding voltage and current for obtaining power equation.

## D. Power Equation

Fig. 9 shows waveforms of the winding voltage and current for obtaining power equation of the proposed converter assuming $V_{C c}=V_{H} / N$. The power equation of DAPWM method can be obtained by the integration of the instantaneous power over one switching period

$$
\begin{equation*}
P_{O}=\frac{3}{T_{S}} \int_{0}^{T_{S}} v_{r o}(t) i_{r}(t) d t \tag{9}
\end{equation*}
$$

where $v_{\text {ro }}$ is the instantaneous voltage across $N_{S 1}$, and the secondary current $i_{r}$ is

$$
\begin{equation*}
i_{r}(t)=\frac{N v_{a n}(t)-v_{r o}(t)}{N^{2} L_{k}} \cdot t+i_{r}(0) \tag{10}
\end{equation*}
$$



Fig. 10. Power flow versus $D_{H}$ and $D_{L}$.
where $i_{r}(0)=0$ and $v_{a n}$ is the instantaneous voltage across $N_{P 1}$. The power equation can be obtained from (9) and (10) by

$$
\begin{equation*}
P_{O}=\frac{V_{H}^{2}\left(D_{H}-D_{L}\right)}{3 f_{S} L_{k} N^{2}} \tag{11}
\end{equation*}
$$

where $f_{S}$ is the switching frequency of the proposed converter. The normalized power equation can be expressed as follows:

$$
\begin{equation*}
P_{O(p . u)}=\frac{D_{H}-D_{L}}{3} \tag{12}
\end{equation*}
$$

where 1 p.u. $=V_{H}^{2} /\left(f_{s} L_{k} N^{2}\right)$. Using (12), the power flow of the proposed converter as a function of $D_{H}$ and $D_{L}$ is plotted as shown in Fig. 10.

## E. Control Strategy

Two control variables, $D_{H}$ and $D_{L}$, are used to control not only power flow but voltage across $C_{c}$. Therefore, circulating current can be reduced by matching voltage across $C_{c}$ with the secondary voltage referred to the primary. Fig. 11 shows the control block diagram of the proposed converter for bidirectional


Fig. 11. Control block diagram of the proposed converter for bidirectional operation. (a) Whole control block diagram with output power regulation. (b) Power flow controller by HVS voltage regulation. (c) Power flow controller by LVS voltage regulation.


Fig. 12. Simulation waveforms showing seamless mode transfer under step power flow reversal.
operation. Fig. 11(a) shows the whole control block diagram consisting of the clamp capacitor voltage $\left(V_{C c}\right)$ controller and the power flow controller. In order to match the voltage across $C_{c}$ with HVS voltage referred to primary side, the reference value of $V_{C c}$ is determined as follows:

$$
\begin{equation*}
V_{C c}^{*}=\frac{V_{H}}{N} . \tag{13}
\end{equation*}
$$

$V_{C c}$ controller was implemented using an average currentmode controller. $D_{L}$ is the output of $V_{C c}$ controller. $D_{H}$ is


Fig. 13. Experimental waveforms of the primary phase currents. (a) Boost mode. (b) Buck mode.


Fig. 14. Experimental waveforms of switch voltages and current in boost mode. (a) LVS. (b) HVS.
determined by adding $D_{L}$ to the output of the power flow controller. A positive output of the power flow controller makes $D_{H}$ be greater than $D_{L}$, leading the converter to operate in boost mode. On the other hand, a negative output of the power flow controller makes $D_{L}$ greater than $D_{H}$, leading the converter to operate in buck mode. The power flow controller can also be implemented with either HVS voltage regulation, as shown in Fig. 11(b), or LVS voltage regulation, as shown in Fig. 11(c).

Fig. 12 shows simulation waveforms illustrating the performance of the proposed closed-loop system. Note that the


Fig. 15. Experimental waveforms of switch voltages and current in buck mode. (a) LVS. (b) HVS.
converter is operating under the worst case operating condition of step power flow reversal. During the boost operation, $D_{H}$ is greater than $D_{L}$. It should be noted that after step power flow reversal, $D_{H}$ decreases smoothly and becomes smaller than $D_{L}$.

## III. EXPERIMENTAL Results

To verify the operating principle of the proposed converter, a $3-\mathrm{kW}$ prototype was built according to the following specification: $P_{o}=3 \mathrm{~kW}, V_{H}=380 \mathrm{~V}, N=2, V_{L}=80-110 \mathrm{~V}$, $f_{s}=50 \mathrm{kHz}, L_{k}=3 \mu \mathrm{H}, \Delta I_{L}=6 \mathrm{~A}$, and $\Delta V_{C c}=2 \mathrm{~V}$.

The current ripple of $L_{f}$ and the voltage ripple of $C_{c}$ can be obtained as follows:

$$
\begin{align*}
\Delta I_{L} & =\frac{V_{H} \cdot\left(D_{L}^{2}-D_{L}+2 / 9\right)}{N \cdot L_{f} \cdot f_{s}}  \tag{14}\\
\Delta V_{C c} & =\frac{2 / 3-D_{L}}{3 \cdot C_{c} \cdot f_{s}} \cdot\left(\frac{P_{O} \cdot N}{V_{H} \cdot D_{L}}-\frac{V_{H}\left(D_{H}-D_{L}\right)}{N \cdot L_{k} \cdot f_{s}}\right) \tag{15}
\end{align*}
$$

Using (14) and (15), the inductance and the capacitance of the prototype are calculated as $L_{f}=18 \mu \mathrm{H}$ and $C_{C}=10$ $\mu \mathrm{F}$. Considering some margin, actual values of $L_{f}=20 \mu \mathrm{H}$ and $C_{C}=18 \mu \mathrm{~F}$ were used, respectively. Both LVS and HVS switches are implemented with IXFN110N60P3 (600 V, 110 A, and $56 \mathrm{~m} \Omega$ ) MOSFET. An off-the-shelf EI core of the ferrite


Fig. 16. Experimental waveforms under LVS voltage variation.


Fig. 17. Experimental waveforms under power flow change.
material is used for the three-phase transformer. Unidentical leakage and magnetizing inductances of each phase of the transformer may cause imbalance in three-phase currents. In order to reduce the imbalance, mismatch in leakage and magnetizing inductances of each phase of the transformer should be made as small as possible. Since the cross-sectional area of the center leg of the core is twice them of the both side legs, the center leg is cut out so as to have equal width [25]. Fig. 13 shows the primary phase current waveforms and interleaved current $I_{\mathrm{L}}$. Note that imbalance among the phase currents is hardly seen even though no current sharing control is employed in the experiment. Figs. 14 and 15 show the experimental waveforms of the boost and buck operations of the proposed converter, respectively. It can be seen that switches are turned ON under ZVS(ZCS) and/or turned OFF under ZCS. Figs. 16 and 17 demonstrate regulation performances under voltage variation and power flow change, respectively. Fig. 16 shows that $V_{C c}$ is well regulated under step changes in LVS voltage. Fig. 17 shows that $I_{L}$ is smoothly changing under step changes in $P_{O}^{*}$. The measured efficiencies for the boost and buck modes are shown in Fig. 18. The measured efficiency in the buck mode is lower than that in the boost mode because the LVS top switches are turned ON with hardswitching in the buck mode, while all switches achieve ZVS or ZCS turn-on in the boost mode. The efficiency was measured using Yokogawa WT3000. The maximum efficiencies of the boost and buck modes are $96 \%$ at 2.5 kW and $95.4 \%$ at 3 kW , respectively. Fig. 19 shows the photograph of the proposed converter.


Fig. 18. Measured efficiency as a function of the output power.


Fig. 19. Photograph of the proposed converter prototype.

## IV. CONCLUSION

In this paper, a new bidirectional three-phase push-pull converter with active clamp that helps achieve not only clamping of surge voltage but soft switching of switches has been proposed. Due to high impedance nature at LVS of the proposed converter, the magnetic core saturation of the transformer is negligible, which makes the proposed converter viable for higher power application.

The proposed DAPWM technique for the bidirectional threephase push-pull converter provides the following advantages: identical switching patterns of boost and buck modes leads to seamless mode change under power flow reversal; circulating currents are reduced by matching the primary voltage with the secondary voltage referred to the primary; and the conventional PWM technique can be employed unlike the PPS method where both phase-shift angle and duty cycle should be controlled, thereby allowing simple implementation. A 3-kW prototype of the proposed converter has been built and tested to verify the validity of the proposed operation. Imbalance among the phase currents has hardly been observed even though no current sharing control is employed in the experiment. The maximum efficiencies measured in the boost and buck modes are $96 \%$ at 2.5 kW and $95.4 \%$ at 3 kW , respectively. According to the
results, the proposed converter could be a promising candidate for high-power isolated dc-dc converter system where bidirectional power flow is required.

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